RandNet-Parareal: a time-parallel PDE solver using Random Neural Networks

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Time parallelization: a crucial technology RandNet-Parareal ar			a glance	
	PDE System	Speed-up over Parareal	$\begin{array}{c} \mathbf{Speed-up} \\ \mathbf{over} \ \mathscr{F} \end{array}$	
	1D Viscous Burgers' 2D Diffusion-Reaction 2D shallow water	x8.6 - x21 x3 - x5 x1.3 - x3.6	x12.6 - x30 x5.4 - x124 x16 - x39	
	Rand	PDE System 1D Viscous Burgers' 2D Diffusion-Reaction 2D shallow water	RandNet-Parareal at a glancePDE SystemSpeed-up over Parareal1D Viscous Burgers'x8.6 - x212D Diffusion-Reactionx3 - x52D shallow waterx1.3 - x3.6	

Integrating data-driven learning can drastically speed-up simulations \longrightarrow

2D & 3D Brusselator x3

x3.4 - x4.4 x249 - x253

Parareal & Existing Approaches

Compute the true solution *sequentially* - slow!



RandNet-Parareal

A better model: random weight neural networks (RandNet) [6]



- Closed form solution for the RandNet output weights
- Universal approximator [7]
- Avoids back-propagation, stable and fast training
- Strong empirical performance

Focus: RandNet-Parareal on 2D Diffusion-Reaction

Approximate the initial conditions *sequentially* - inaccurate but fast



Estimate the solution in parallel - fast but still imprecise



Here, u = u(t, x, y) is the activator with coefficient D_u and reaction function $R_u = R_u(u, v)$. Similarly for the inhibitor v = v(t, x, y)

 $\partial_t u = D_u \partial_{xx} u + D_u \partial_{yy} u + R_u, \quad \partial_t v = D_v \partial_{xx} v + D_v \partial_{yy} v + R_v,$



Let \mathscr{F} be an accurate, slow numerical solver and \mathscr{G} be an imprecise, fast one. Parareal [3] updates the solution U_i^k at time t_i iteration k as



 $(\mathscr{F} - \mathscr{G})(\cdot)$ is approximated using previous iteration data, inaccurate $(\mathscr{F} - \mathscr{G})(\underbrace{\mathcal{V}_{i-1}^k}_{i-1})$ vs $(\mathscr{F} - \mathscr{G})(\underbrace{\mathcal{V}_{i-1}^{k-1}}_{i-1})$

GParareal [4]: Approximate ℱ - 𝔅 using Gaussian processes (GP)
Faster convergence but expensive to train at O(N³) cost
nnGParareal [5]: Approximate ℱ - 𝔅 using a k-nearest neighbors GP
Reduced cost O(k³), k ≪ N, but not scalable to high-dimensions

References

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